## **Problem Set 9: Momentum and Collision Theory, Rigid Bodies, Kinematics**

Design Engineering Challenge: "The Big Dig" 2.007 Contest Ball Pyramid breaking Concepts

PROBLEM 1:

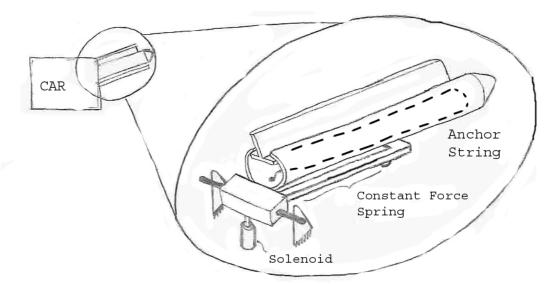


Figure 1: Projectile Mechanism

Not retractable. One shot, rapid deployment, little room for error, misalignment. Would be better if could rapidly retract, but is not feasible. Far from target.

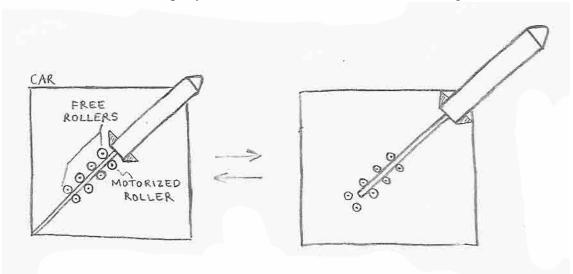


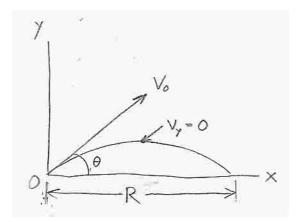
Figure 2: Telescope Mechanism

Retractable, multiple attempt fairly rapid deployment, room for error/ misalignment.

Can rapidly retract but not so important. Direct contact with target.

## PROBLEM 2:

Projectile:



 $V_{ox} = V_o \cos \boldsymbol{q}$  $V_{oy} = V_o \sin \boldsymbol{q}$ 

At highest point,

$$V_{y} = V_{o} \sin \boldsymbol{q} - gt = 0$$
$$t = \frac{V_{o} \sin \boldsymbol{q}}{g}$$

at R, total time T=2t where T= time to target

$$R = (V_o \cos \boldsymbol{q})T = \frac{2V_o^2(\sin \boldsymbol{q} \cos \boldsymbol{q})}{g} = \frac{V_o^2(2\sin \boldsymbol{q} \cos \boldsymbol{q})}{g} = \frac{V_o^2\sin 2\boldsymbol{q}}{g}$$

Telescope:

Rotational:  $T = \frac{2p}{w}$  C = 2pR where, ? = rpm of motor and R = radius of wheel.

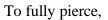
Translational:  $V = \mathbf{w}R$   $t = \frac{L}{V} \Longrightarrow t = \frac{L}{\mathbf{w}R}$  prong extension

$$T = \frac{D}{wR}$$
 time to target

## PROBLEM 3:

$$KE = \frac{1}{2}mV^2$$
$$PE = Mgh$$

Where, m: mass of car M: mass of stack h: height of center of mass of stack V: velocity of car



Conservation of energy (negligible losses)

$$\frac{1}{2}mV^2 = Mgh \Longrightarrow V = \sqrt{\frac{2Mgh}{m}}$$

Conservation of momentum (perfectly elastic) M

$$mV_{car} = mV_{stack} \Longrightarrow V_{car} = \frac{M}{m}V_{stack}$$

## PROBLEM 4:

An experiment can be observed to verify conversation of energy approach. Run car at calculated velocity and see if stack is fully pierced.

